

# Energy-Optimal Cavity Filling

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LUND UNIVERSITY



EUROPEAN  
SPALLATION  
SOURCE

## OVERVIEW

Pulsed, high-power accelerators consume significant amounts of power to fill the cavities, power which does not contribute to particle acceleration. A recent paper [1] considered how to minimize the *reflected* power during filling, which essentially corresponds to minimizing the energy consumption of an ideal amplifier. We demonstrate how to find optimal filling profiles for *arbitrary* efficiency characteristics, and also in presence of detuning (assumed to be repetitive and known). The results on this poster has been previous published in [2].

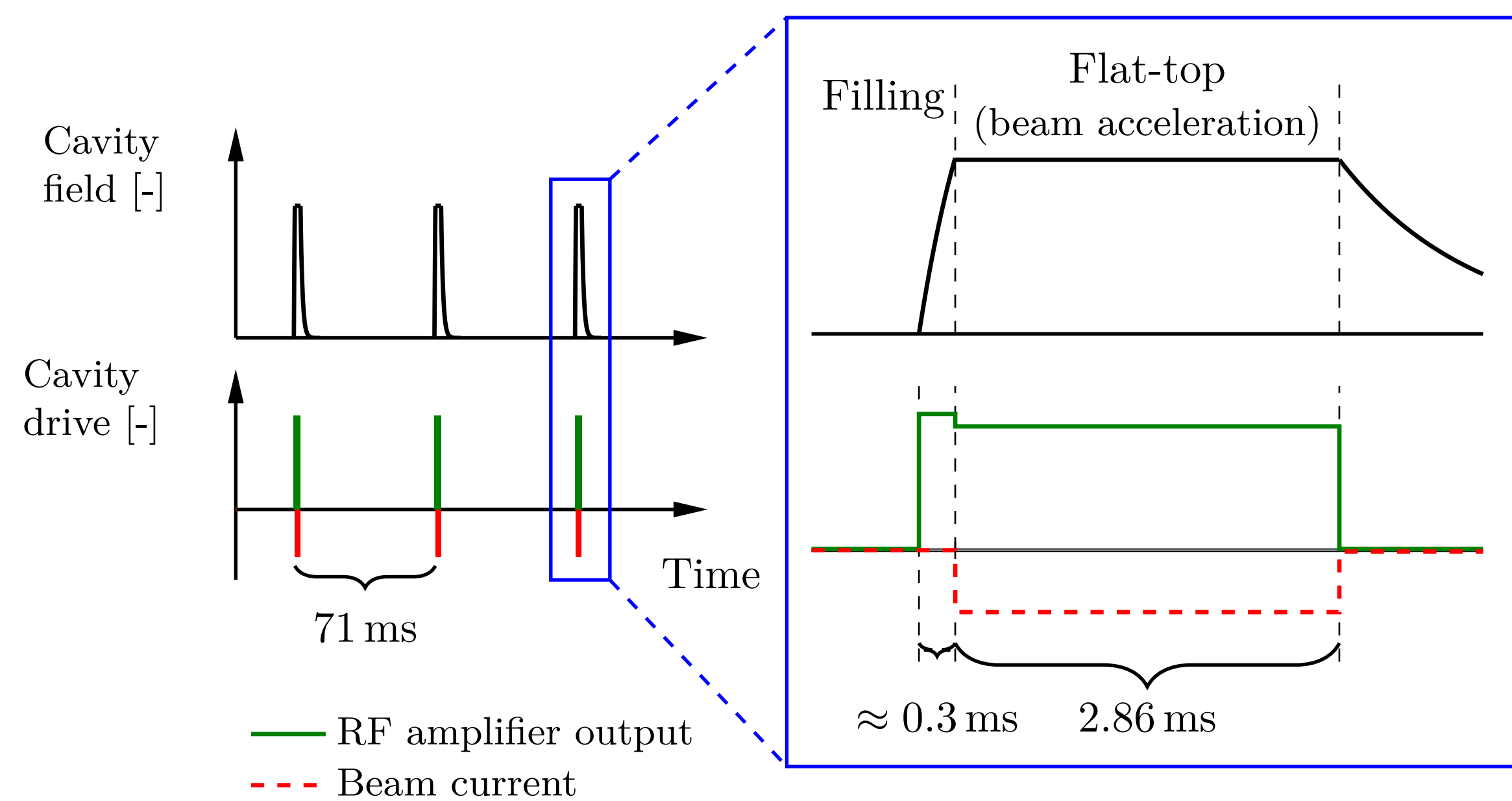
## EXAMPLE: EUROPEAN SPALLATION SOURCE

### ESS Parameters

Beam Current	62.5 A
Pulse length	2.86 ms
Pulse rate	14 Hz
Average Beam Power	5 MW
Final Energy	2 GeV
# SRF Cavities	146
Construction cost	≈2 B€



Pulse structure:



► Total electricity cost for filling the 84 high- $\beta$  cavities powered by inductive output tubes (IOTs): **100 k€/year**

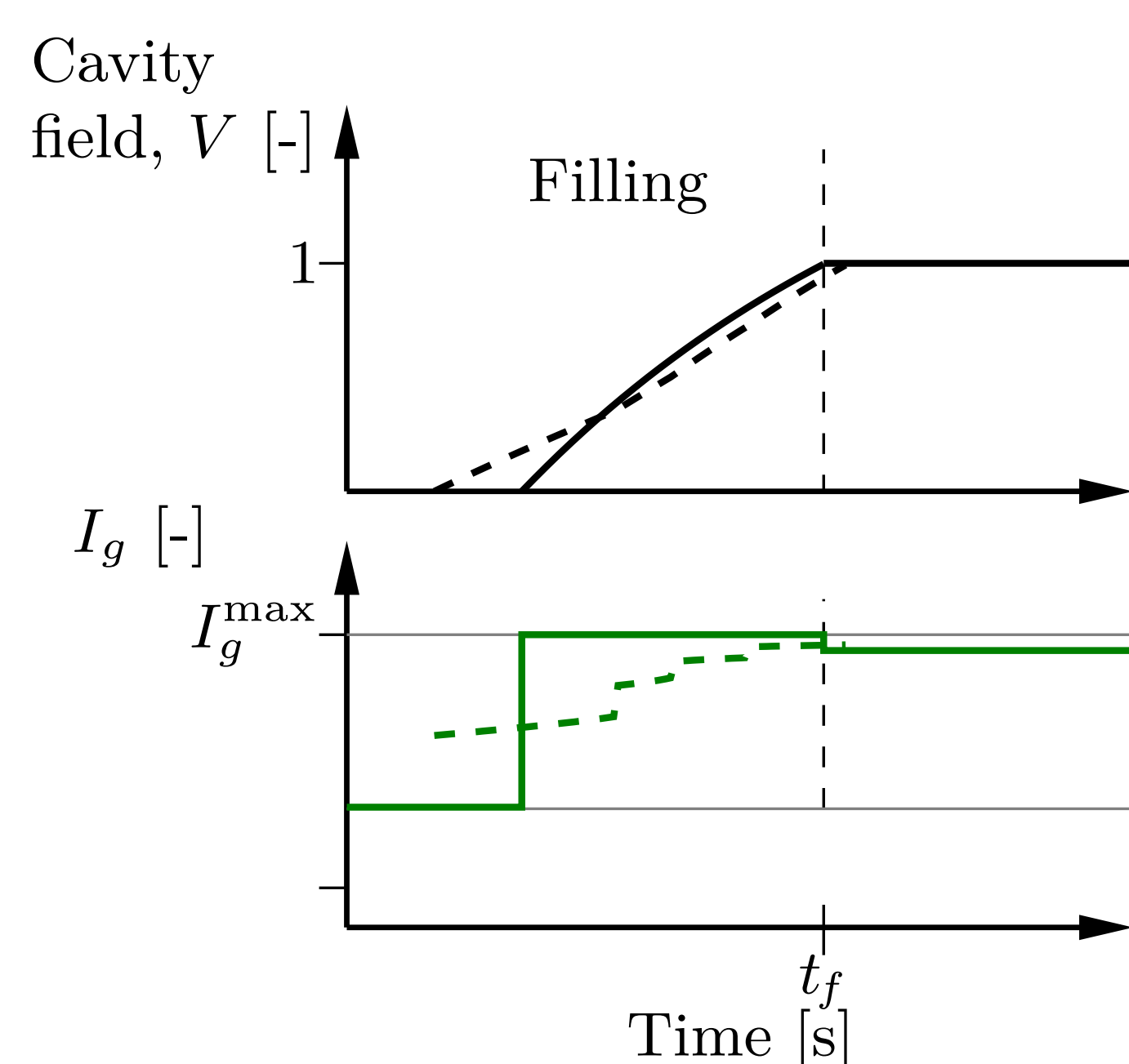
## OPTIMAL CONTROL PROBLEM (AMPLITUDE)

Cavity dynamics during filling (no beam), normalized wrt time and amplitude:

$$\dot{V}(t) = -V(t) + I_g(t)$$

Optimal control problem:

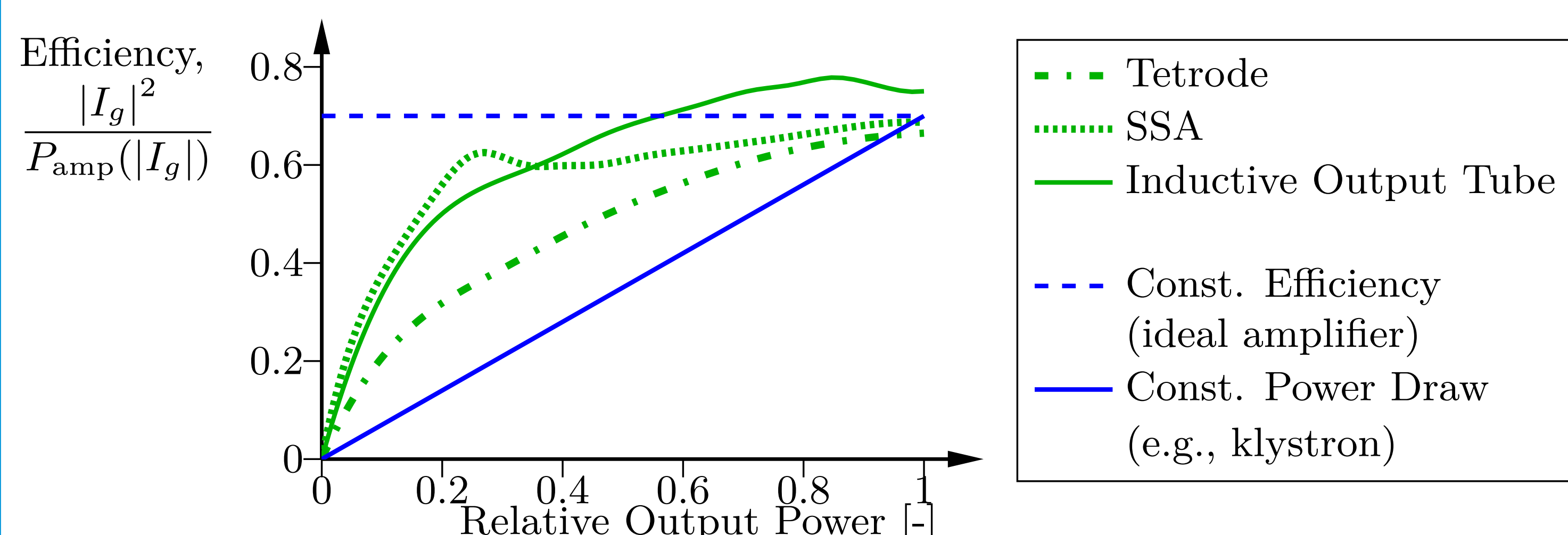
$$\begin{aligned} & \text{minimize}_{I_g, t_f} \int_0^{t_f} P_{\text{amp}}(|I_g|) dt \\ & \text{subject to} \quad \dot{V}(t) = -V(t) + I_g(t) \\ & \quad |I_g(t)| \leq I_g^{\max} \\ & \quad V(0) = 0 \\ & \quad V(t_f) = 1 \end{aligned}$$



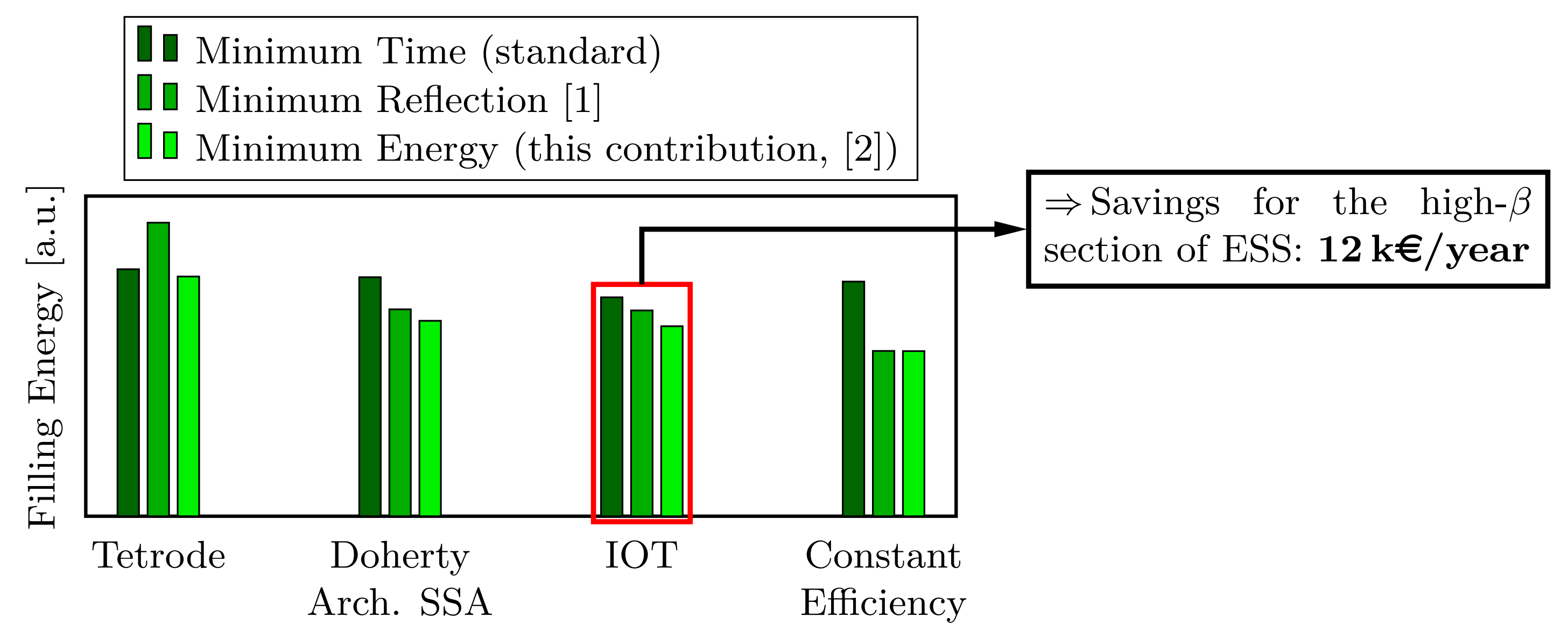
Energy-optimal control signal:

$$I_g^*(t) = \operatorname{argmax}_{I_g} \frac{-V(t) + I_g}{P_{\text{amp}}(I_g)}$$

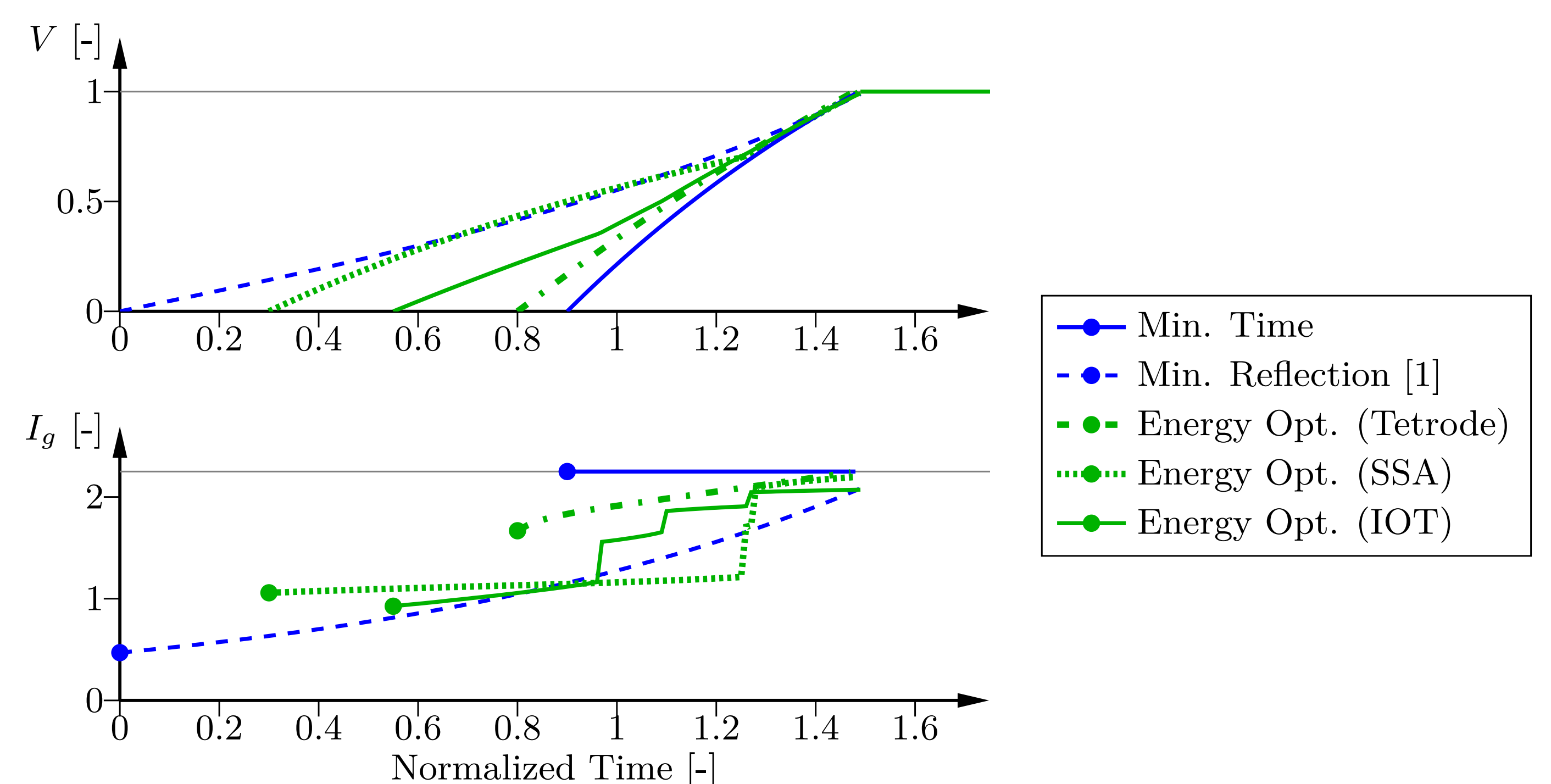
## TYPICAL EFFICIENCY CHARACTERISTICS



## RESULTS



Optimal filling profiles:



## ACCOUNTING FOR DETUNING

Accounting for detuning gives **complex-valued** cavity dynamics:

$$\begin{aligned} & \text{minimize}_{\mathbf{I}_g, t_f} \int_0^{t_f} P_{\text{amp}}(|\mathbf{I}_g|) dt \\ & \text{subject to} \quad \frac{d}{dt} \mathbf{V} = (-1 + i\Delta\omega(t))\mathbf{V} + \mathbf{I}_g \\ & \quad |\mathbf{I}_g| \leq I_g^{\max} \\ & \quad \mathbf{V}(0) = 0 \\ & \quad \mathbf{V}(t_f) = 1. \end{aligned}$$

Can decouple problem by introducing polar coordinates,  $\mathbf{V}(t) = V(t)e^{i\phi(t)}$  and  $\mathbf{I}_g(t) = I_g(t)e^{i\theta(t)}$

Optimal angle for control signal:

$$\theta^*(t) = - \int_t^{t_f} \Delta\omega(t) dt$$

## REMARKS

- Due to the longer fill time, the cryogenic load is increased. For ESS:  $\approx 1\text{--}2\text{ k€/year}$
- The proposed filling approach requires good knowledge of the system parameters, and that the detuning  $\Delta\omega(t)$  is known and repetitive (low gain feedback would reduce the impact of microphonics)

## BIBLIOGRAPHY

- [1] Bhattacharyya, A.K., Ziemann, V., Ruber, R., and Goryashko, V. (2015). “Minimization of power consumption during charging of superconducting accelerating cavities”. Nuclear Instruments and Methods in Physics Research A, 801, 78–85.
- [2] OT, BoB (2017). “Energy-Optimal Excitation of Radio-Frequency Cavities”. Proceedings of the IFAC World Congress 2017.