

Development of a high-performance gantry system for a new generation of optical slope measuring profilers

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Outline

Motivation and goals

Specification development

Gantry system and motion control

Enclosure and environment control

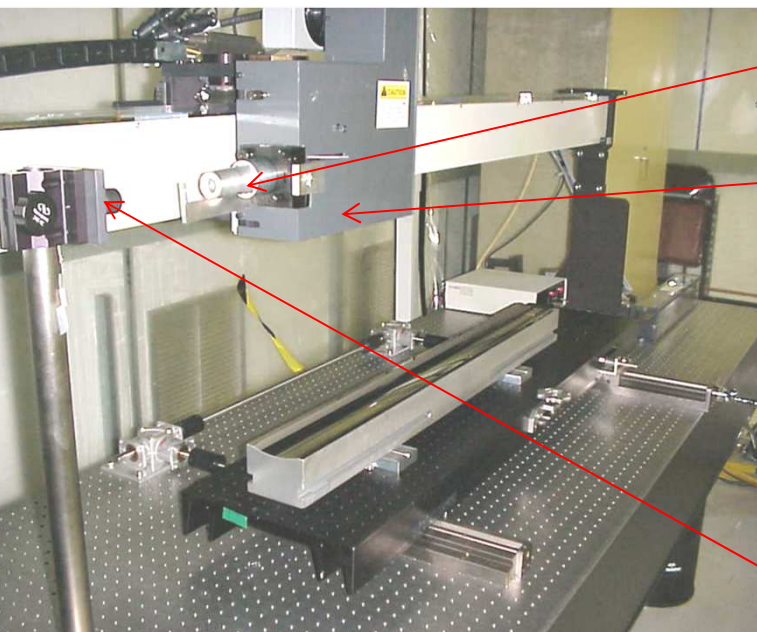
Data acquisition and analysis software

Preliminary tests and results

- Temperature survey
- Characterization of the gantry system

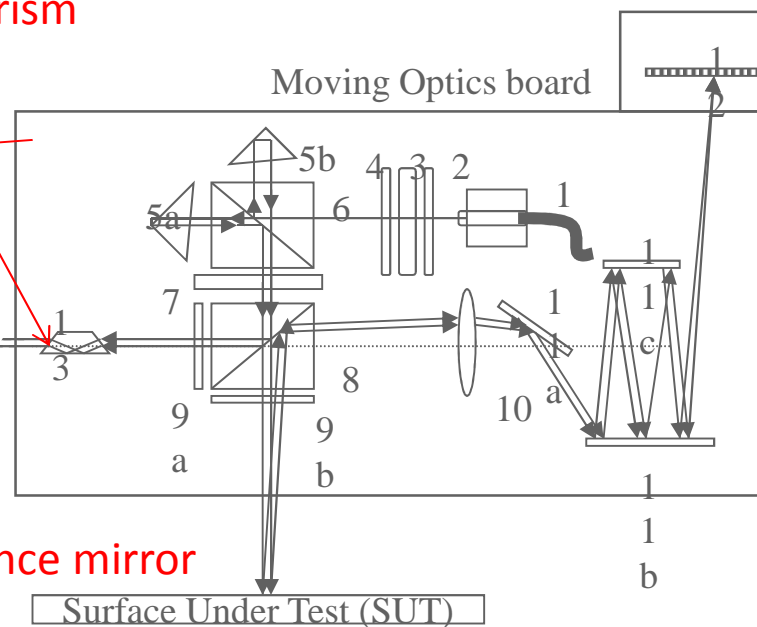
Summary and future work

The APS Long Trace Profiler (LTP-II)



Dove prism

Reference mirror



Acquired in 1994 from Continental Optic, Inc.

Dove prism added in the reference arm in 1996 to compensate for thermal drift

- Noise level is $\approx 0.3 \mu\text{rad}$.
- Systematic error $> 0.5 \mu\text{rad}$ due to imperfections in the optical elements of the optics board.
- Non linearity

It is ready to retire!

step to upgrade APS LTP attempted in 2009-10 with modest budget and objective

h-Pierre Rock* and Lahsen Assoufid , APS LTP -II Upgrade Conceptual Design

ort, Internal Report, Argonne National Laboratory, 2010

hmer Student 2009 and 2010, University of Maryland

Scanning Pentaprism

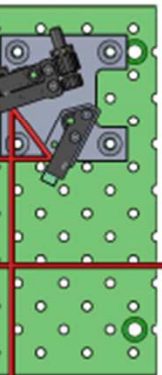
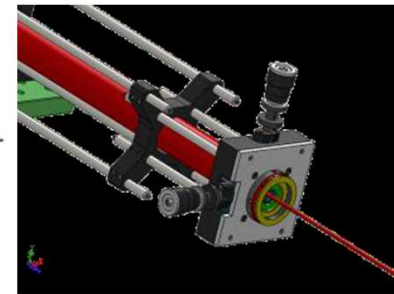


Table 2: Change in length as a function of temperature.

$\Delta^{\circ}\text{C}$	ΔL (μm)		
	Carbon steel		Granite
	min	max	
0.5	2.955	4.954	1.104
1.0	5.909	9.909	2.209

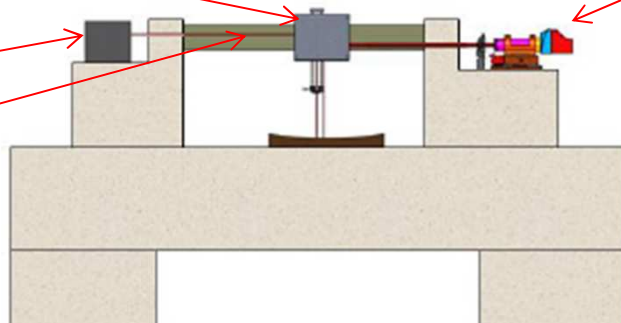


Diaphragm for the AC

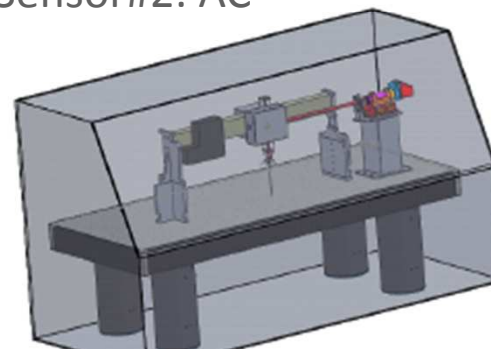
Another addition to the system could be to place a thermal enclosure for the LTP within the existing thermal enclosure of the metrology laboratory to have a more precise temperature control. An illustration of future work is shown below.

I Sensor#1

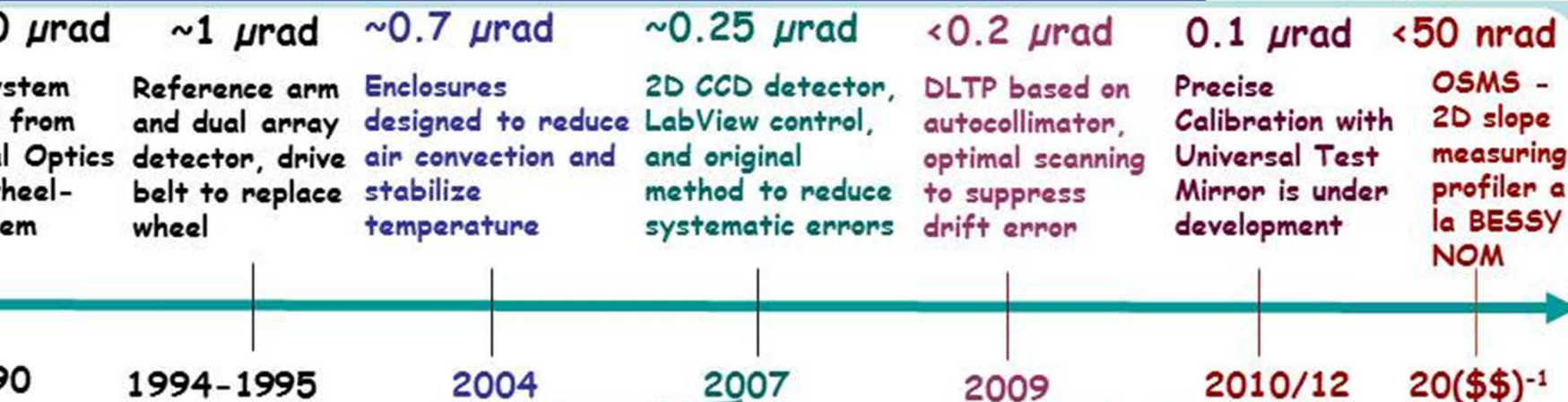
g LTP-II
ic bridge



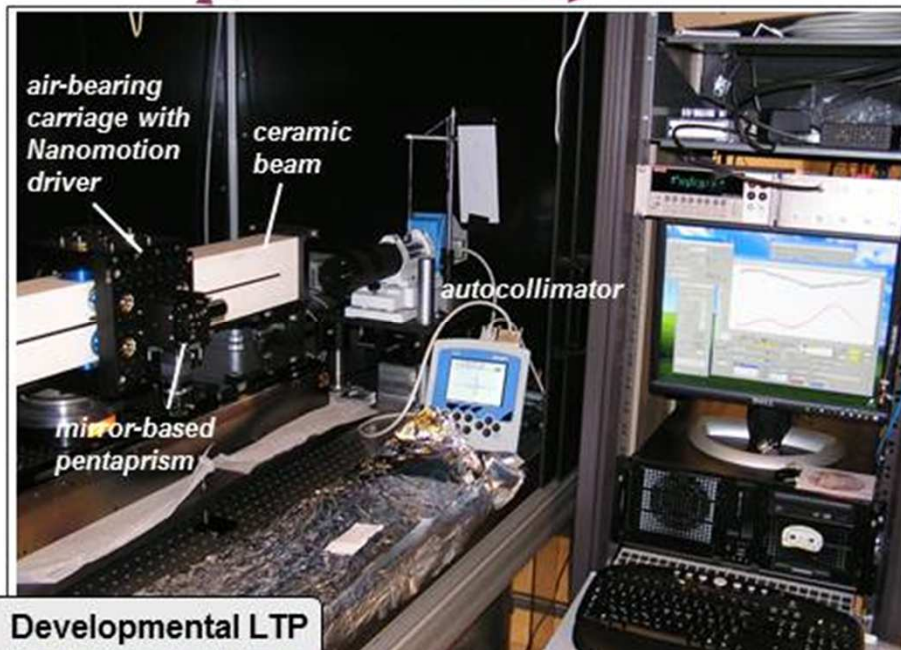
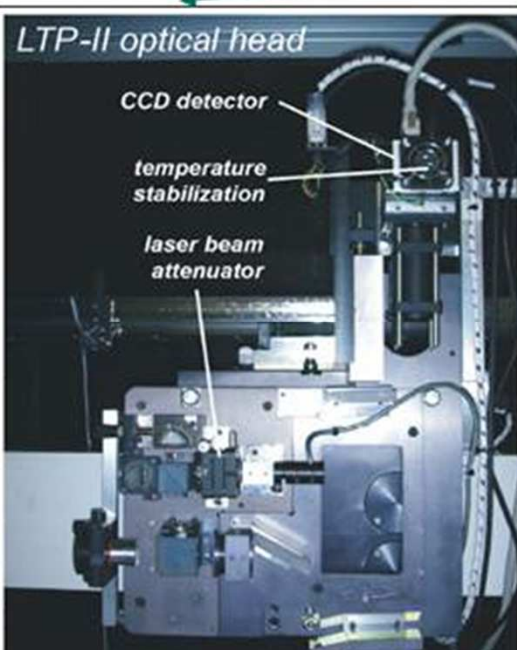
Sensor#2: AC



Development of Surface Slope Profilers at the ALS OML



ALS LTP-II





The Development of Specification for OSMS: 1st meeting at LBL/ALS, March, 26 2010

Collaborative efforts of metrology groups at DOE Labs

Active participation of industrial vendors of x-ray optics and metrology instrumentation and others

Goals of the meeting:

- Discuss the development of new generation of optical slope measuring system (OSMS);
- Solidify the OSMS design approaches that will meet the needs of tight mirror specifications and also be affordable for all parties involved, both manufacturers and metrology labs; and
- Put together a common specification for fabrication of a high performance metrology gantry system for OSMS
 - Designed to accommodate multiple sensors to cover a wide range of measurement needs in 1-D and 2-D.
 - Capable of <50 nrad absolute accuracy

st Meeting at Argonne/APS, May 6, 2010

...to finalize the specifications.



Valeriy V. Yashchuk, Peter Z. Takacs, Wayne R. McKinney, Lahsen Assoufid, Frank Siewert and Thomas Zeschke "Development of a new generation of optical slope measuring profiler," NIMA 649 (S1): 152-155 (2011)



Design of the Gantry System

Gantry system with two carriages operating in master-slave mode

- One carriage for slope sensors
- One carriage for long cables and air supply lines for the airbearing
 - Avoids cables torque and motion-induced perturbations

High precision X-linear motor driven carriage with air bearing with 1.5 m scan range:

- 50 nm step size, 50 kg capacity

High precision Y-linear motor driven mirror support table system with air bearing with 300 mm scan range:

- 50 nm step size, 100 kg capacity (to accommodate large mirror bender assemblies)

Mirror kinematic support tip/tilt table with 180 degree rotation platform, fully motorized

- Tip/tilt with 1 μ rad step size

Low thermal extension, highly stable granite

Galeriy V. Yashchuk, Peter Z. Takacs, Wayne R. McKinney, Lahsen Assoufid, Frank Siewert and Thomas Zeschke “Development of a new generation of optical slope measuring profiler,” NIMA 649 (S1), 153-155 (2011).

The Gantry System Design

System with separate carriages: one for the sensors and one for the cables

Bearing
Technology

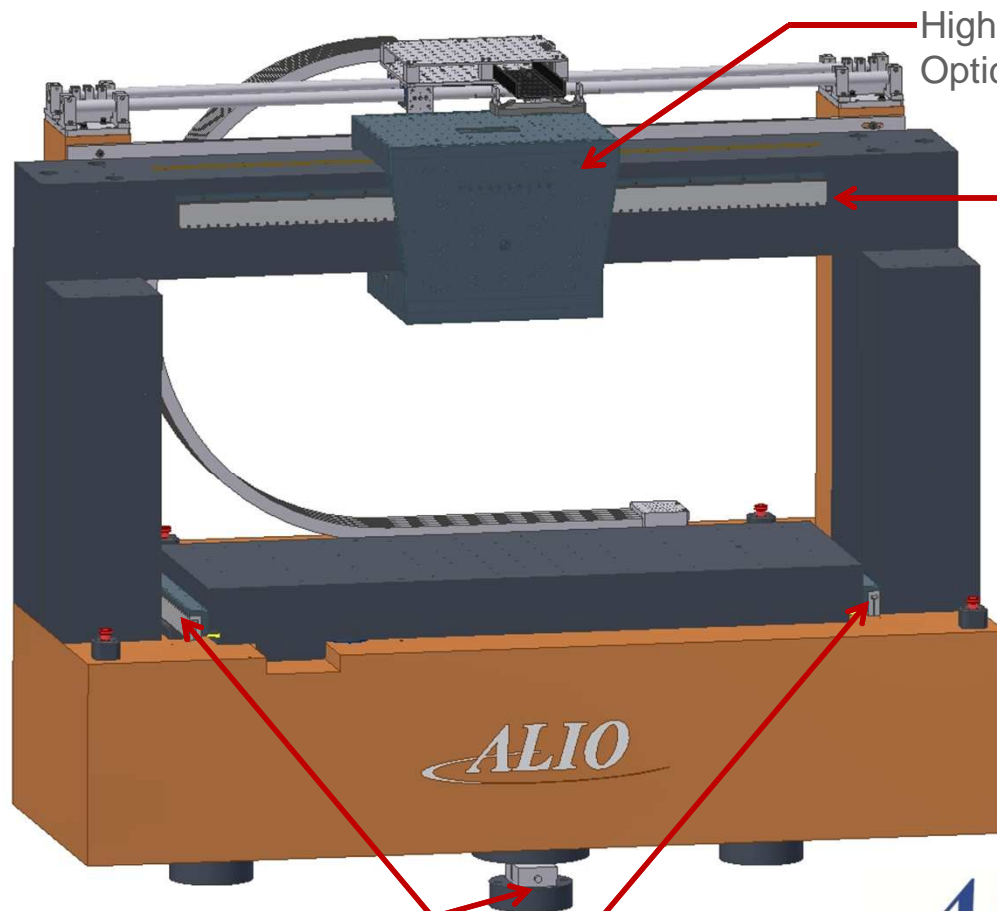
Advanced Servo Control

High Stiffness, Highly Rigid,
Optics Carriage.

Motors (Front and Back
of Granite Beam) Drive
Thru the Center of the
Moving Mass.

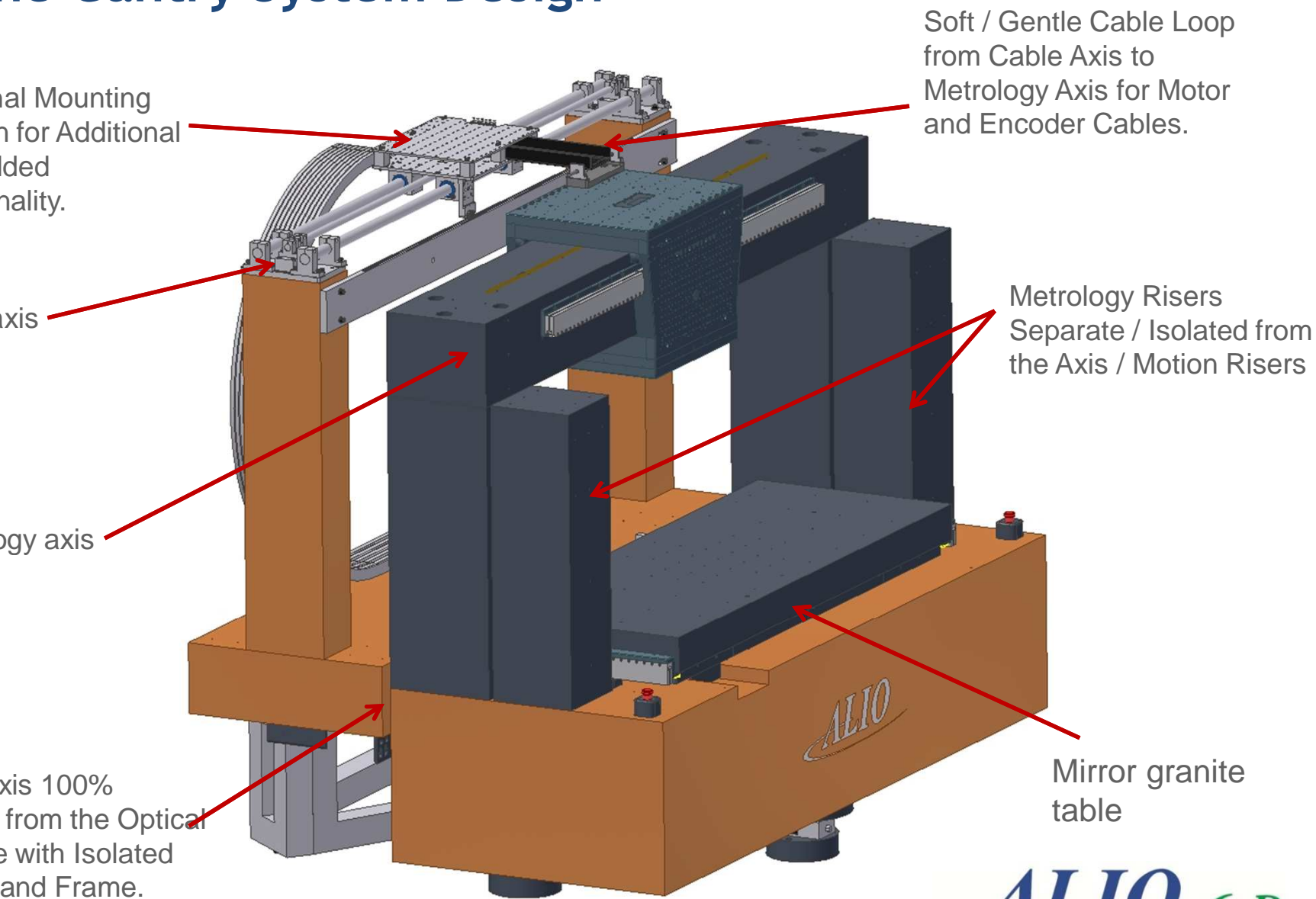
Advanced Kinematic Machine
Tool Mount for 3-Point
Leveling Capability.

Y – Y' Granite Platen Drives for Sub Arc-



ALIO 6-D

The Gantry System Design

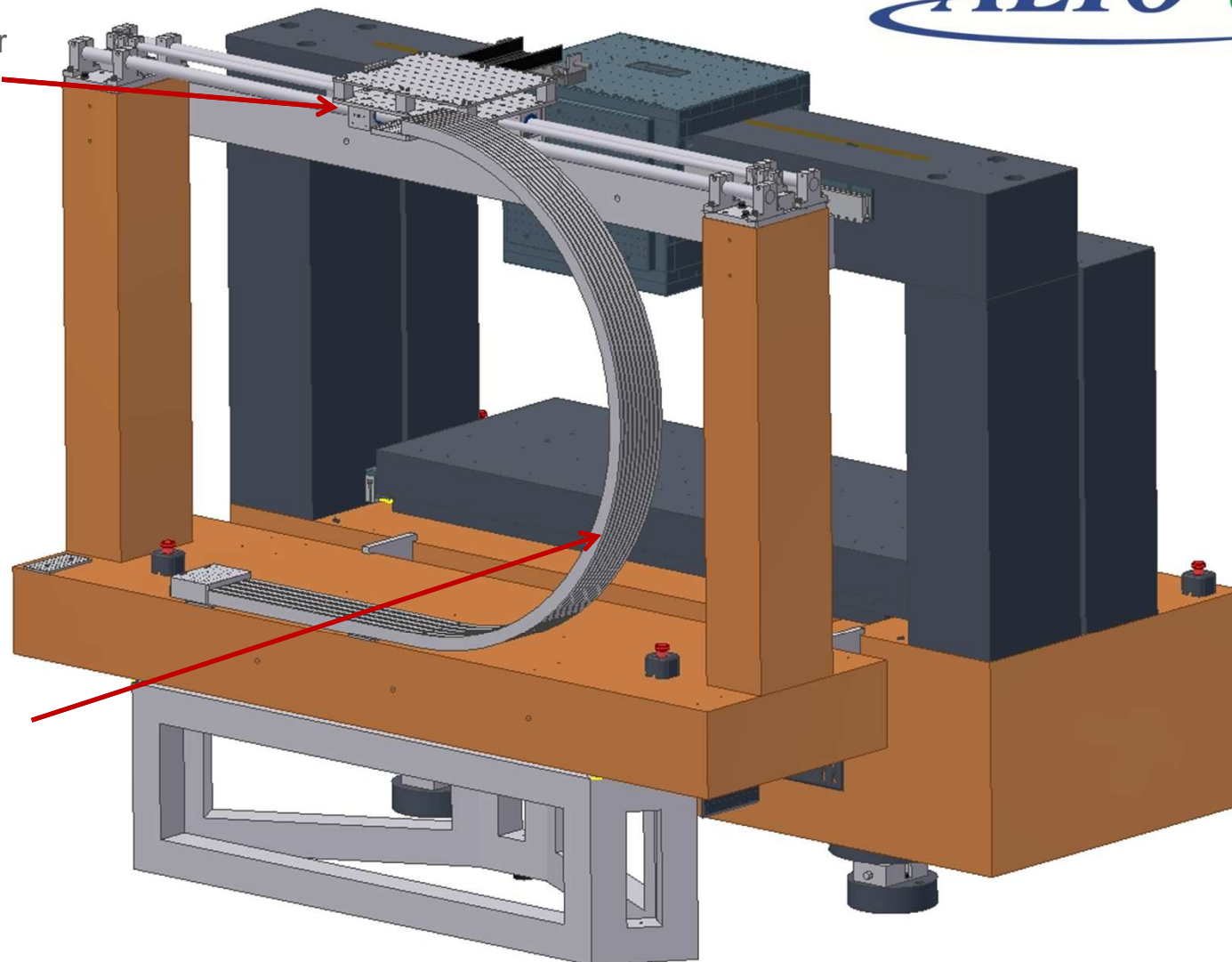


The Gantry System Design

ALIO 6-D

ely Separate Air
Servo Axis for
is. Axis Mirrors
f Optical
Thus Isolating
ag and

Radius Cable
to Minimize
ion and Drag.



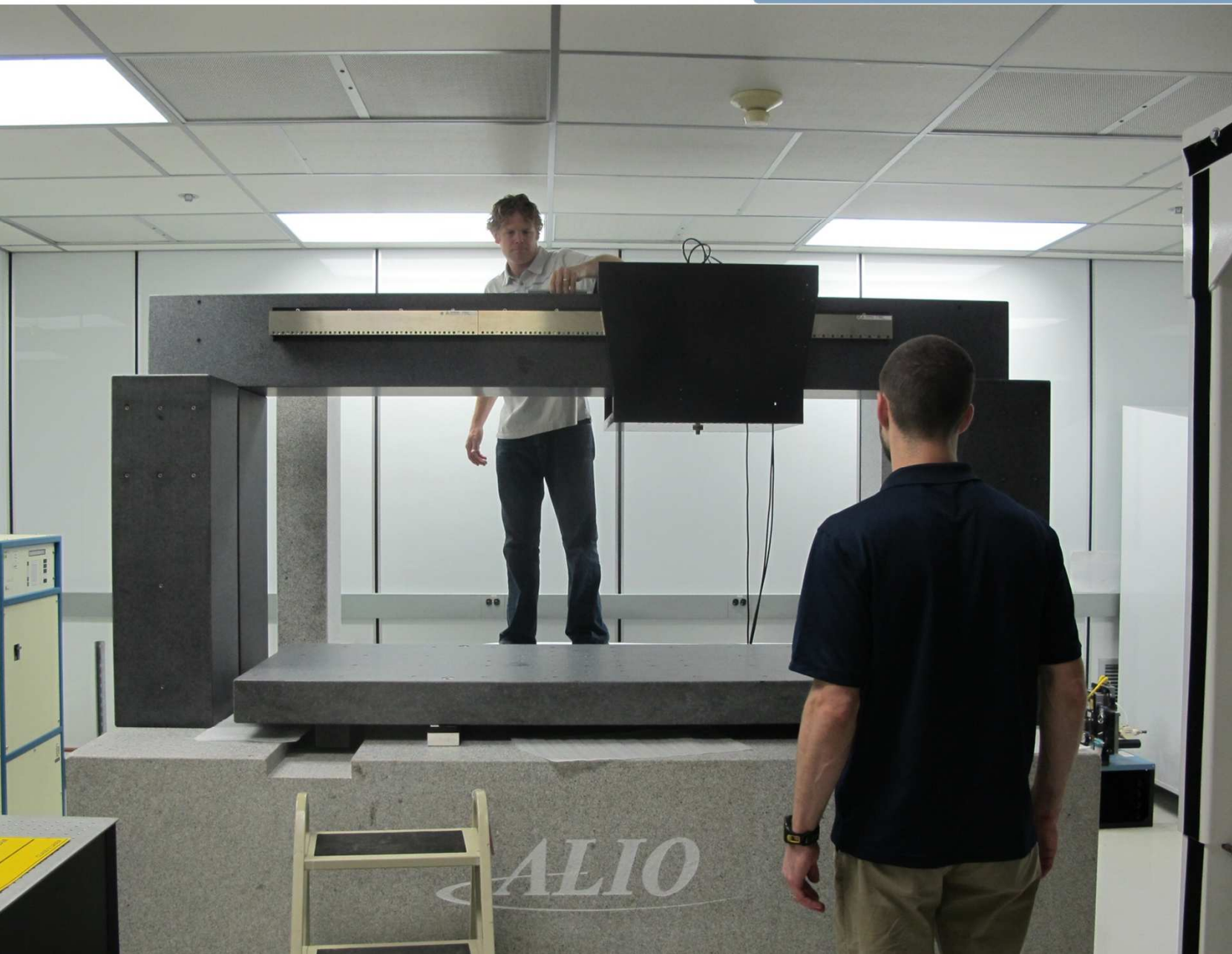
Delivery of the gantry system: August 2011



allation September 2011





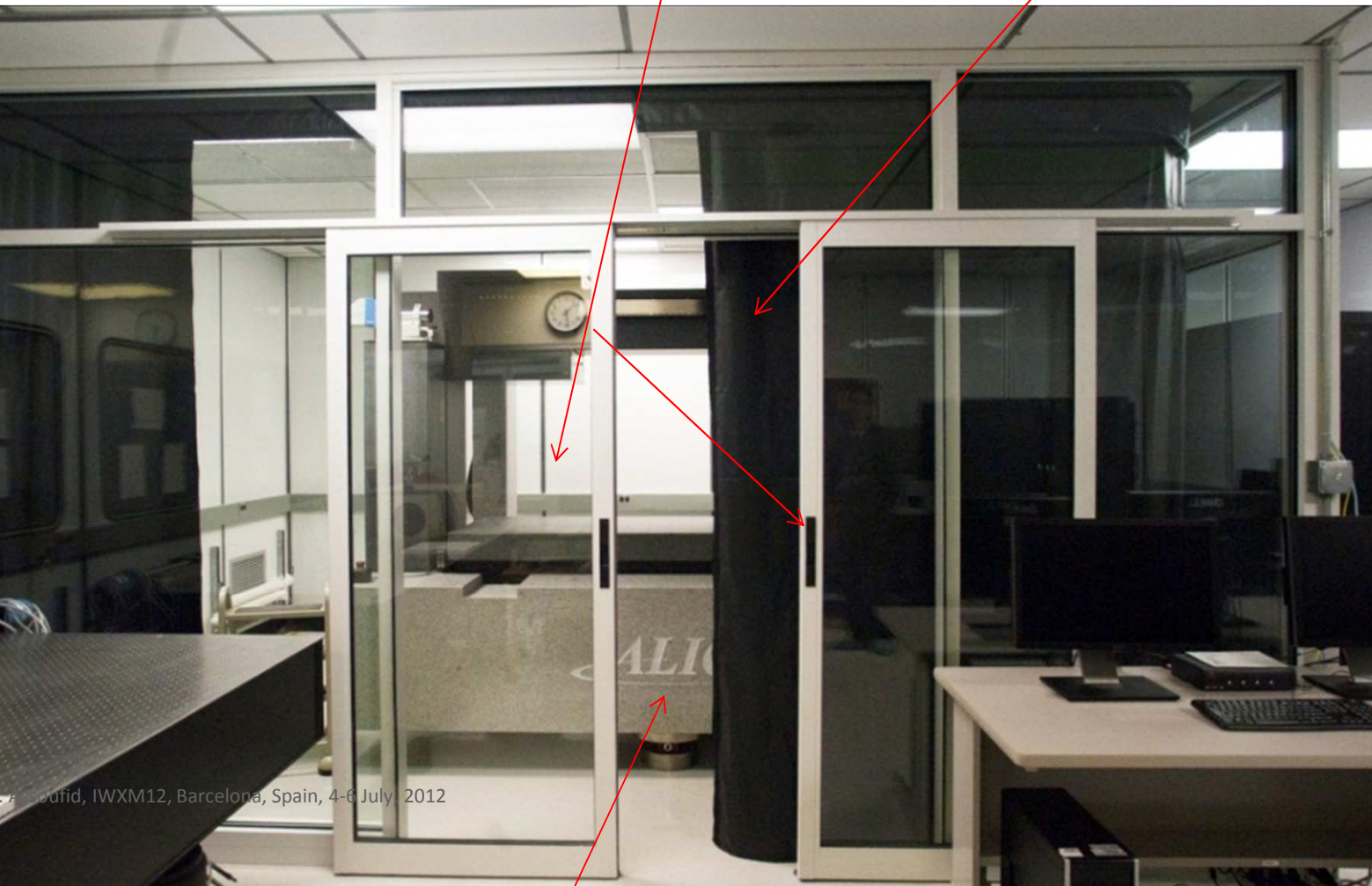


Construction of the Enclosure (October 2011)



nclosure

ompleted November 2011



Double sliding doors

Laser curtain/visible light shield

Granite table

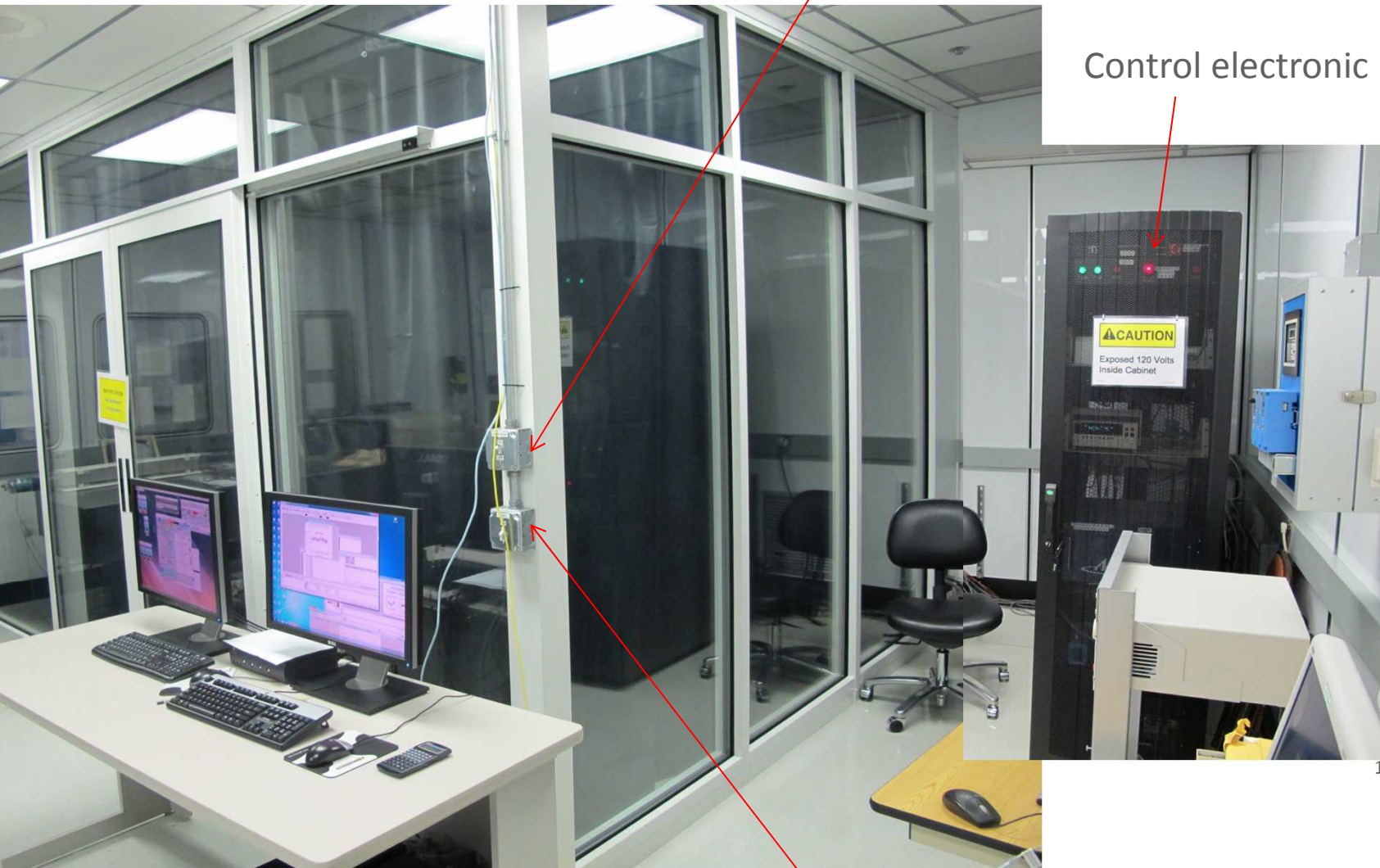
A. Boufid, IWXM12, Barcelona, Spain, 4-6 July 2012

nclosure

Completed November 2011

Light switch

Control electronic



Switch for air flow system (baffle)

PICS-based Data Acquisition

Scan Start/Status

motor2x.adl

Alto X (ltp:SM1)	Alto Y (ltp:SM2)
550.00002	0.09618
550.00000	0.00000
< 2.00000 >	< 5.00000 >
More STOP	More STOP
Scan Ld Go Abort	Scan Ld Go Abort

motor3x.adl

Tilt (ltp:SD)	Tip InBoard (ltp:SD)	Tip InBoard (ltp:SD)
12130	0.00030	0.00000
< 0.00150 >	< 0.00200 >	< 0.00200 >
More STOP	More STOP	More STOP
Scan Ld Go Abort	Scan Ld Go Abort	Scan Ld Go Abort

Measurement Scan

ltp: Measurement Scan

Load Scan GO PAUSE ABORT

SCAN Complete

Scan 1 of 1

Measurement Position 56 of 56

X Position (mm) 549.9999

Y Position (mm) 0.09628

X Slope (micronrad) 11.912

Y Slope (micronrad) -5.827

Temperature (C) 20.9210

ZeroSet Restore

Scan Setup

Start 0.00000 mm

End 550.00000 mm

Increment 10.00000 mm

Settling Time 0.3000 sec

Number of Samples to Average 50

Number of Scans 1

Backward Mode

Rotation Return

Sequence Select 1

Forward Only

Forward/Backward

FWD-BCK-BCK-FWD

F-B-B-F-B-F-F-B

Alignment Positions

Load	Rotation	Tilt	Tip OB	Tip IB
Forward	0.00000 deg	0.00000	0.00000	0.00000
Backward	0.00000 deg	0.00000	0.00000	0.00000
Current	-0.00023	-0.00030	-0.00000	0.00000

ZeroSet Restore

Data File

Save Data Subdirectory 2012_LTP/For_User E

Base Name La_Test

Next scan number 5

Save status Active

Wrote data to La_Test0004.mda

Mirror Measurements

ltp:scan1 ltp:ElcomatAM1:Xavg.VAL

ltp:ElcomatAM1:Yavg.VAL

Plot Plot

Motor Positions

ltp:scan1 ltp:SM1.VAL

ltp:SM2.VAL

ltp:m1.VAL

Plot Plot Plot

Room Temperature

ltp:scan1 ltp:D1Ch2_raw.VAL

ltp:D1Ch3_raw.VAL

ltp:D1Ch4_raw.VAL

ltp:D1Ch5_raw.VAL

ltp:D1Ch6_raw.VAL

Plot Plot Plot Plot Plot

Elapsed Time

ltp:scan1 ltp:timer1:elapsedSecs

Plot

Data Plot

Windows

scanDetPlot.adl

ltp:scan1 Y=ltp:ElcomatAM1:Xavg.VAL

14

12

10

8

6

4

2

0

ltp:SM1.VAL

scanDetPlot.adl

ltp:scan1 Y=ltp:ElcomatAM1:Yavg.VAL

1.0

0.5

0.0

-0.5

-1.0

-1.5

-2.0

-2.5

-3.0

-3.5

-4.0

-4.5

-5.0

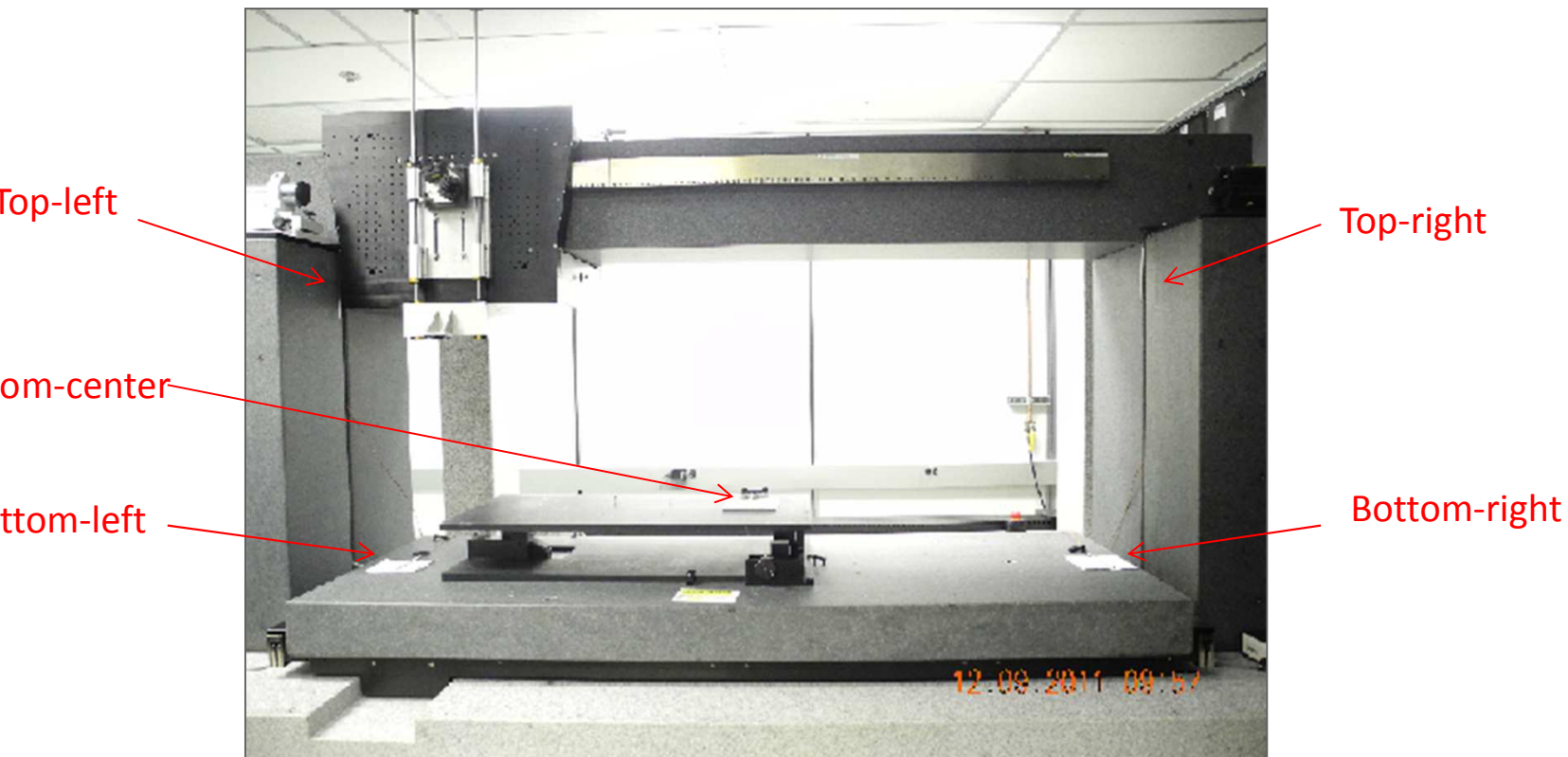
ltp:SM1.VAL

Slope Data

Temperature monitoring and stability

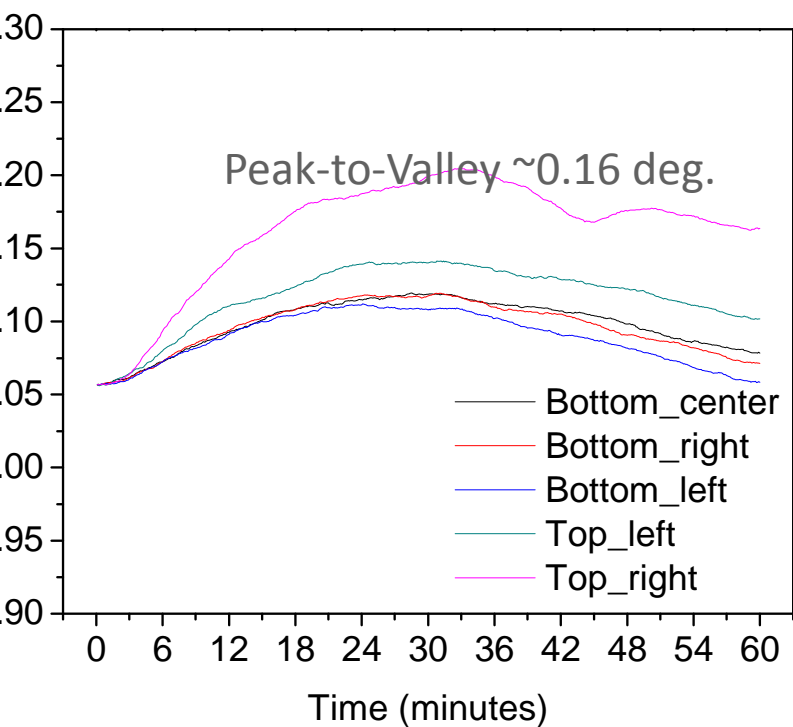
Survey with both temperature point probes (placed around the measurement volume) and an IR Camera.

Measurements performed under various conditions and duration

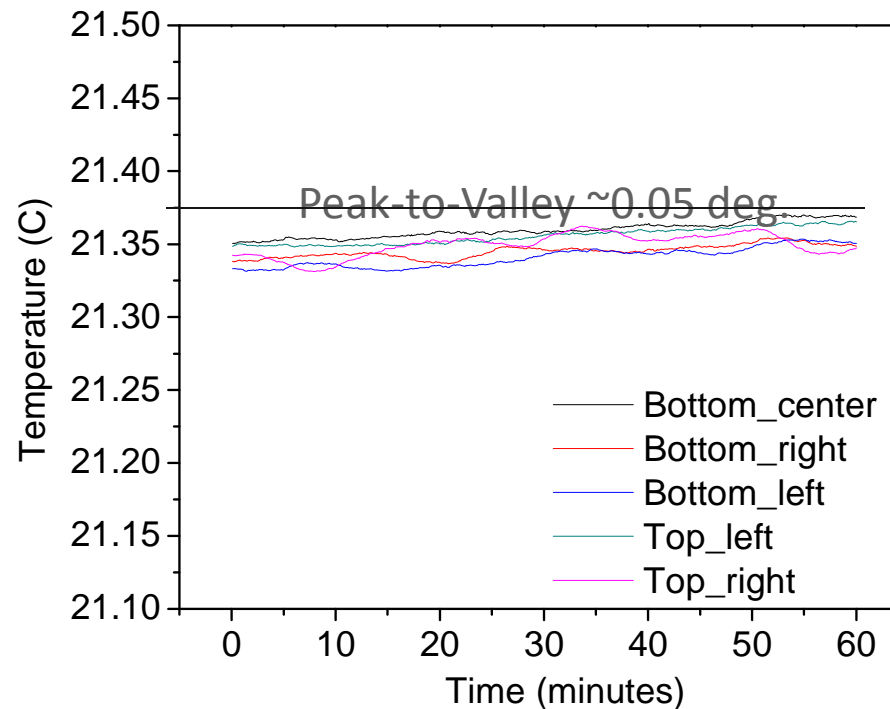


First temperature stability survey (January 2012)

Measurement with temperature point probes over 60 minutes

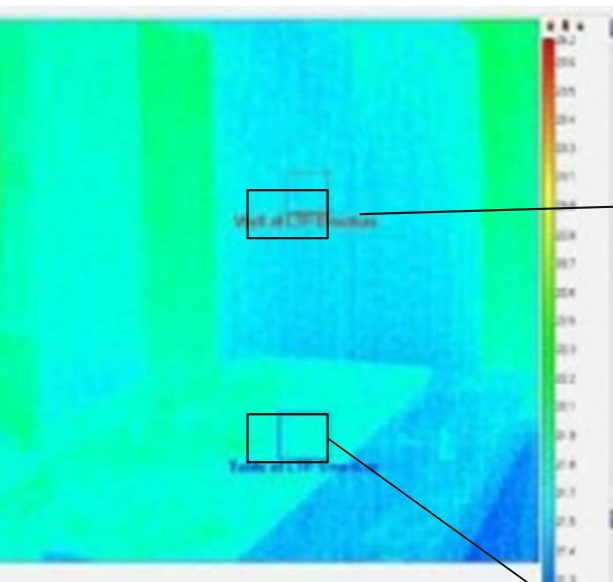


Room AC on; Enclosure AC on;
Enclosure door closed



Room AC on; Enclosure AC off;
Enclosure door closed

First temperature stability survey with IR Camera

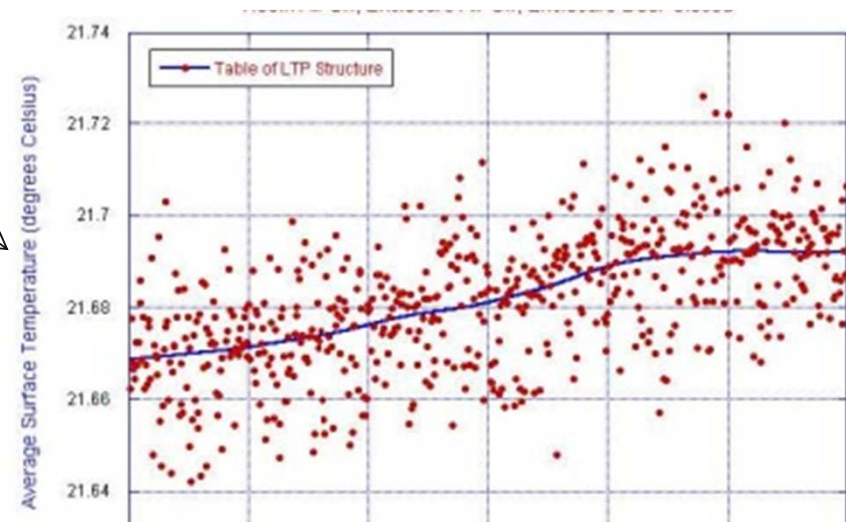
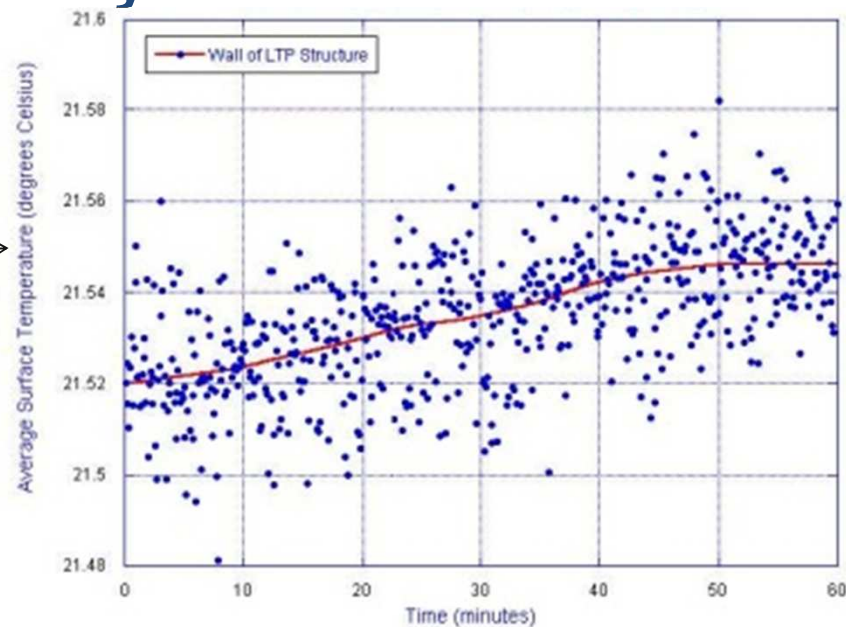


Granite Post

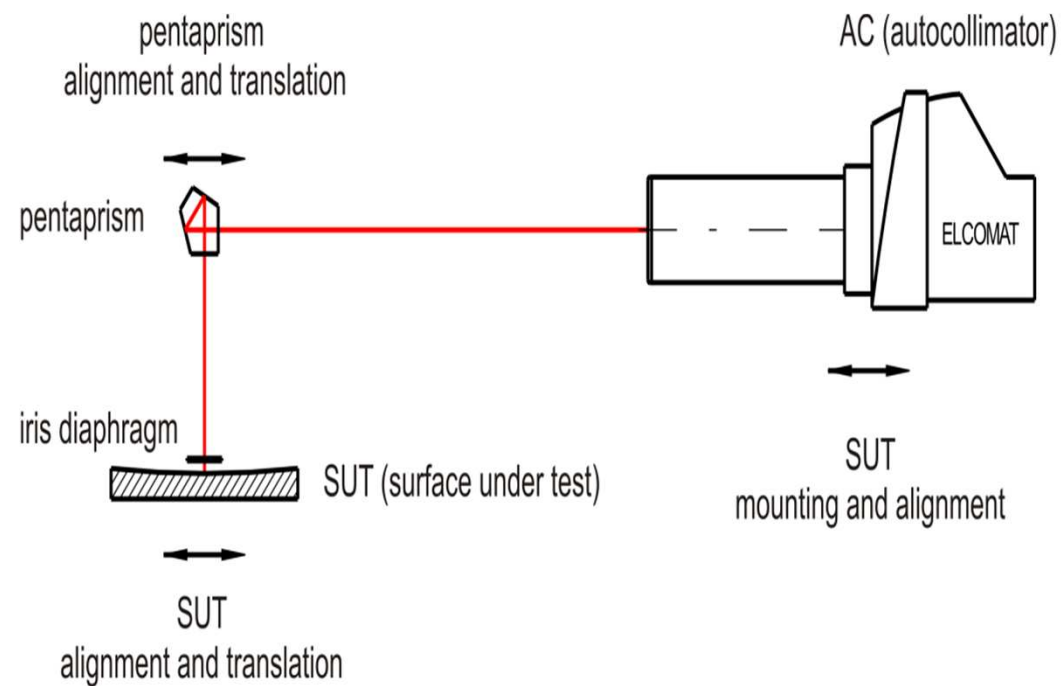
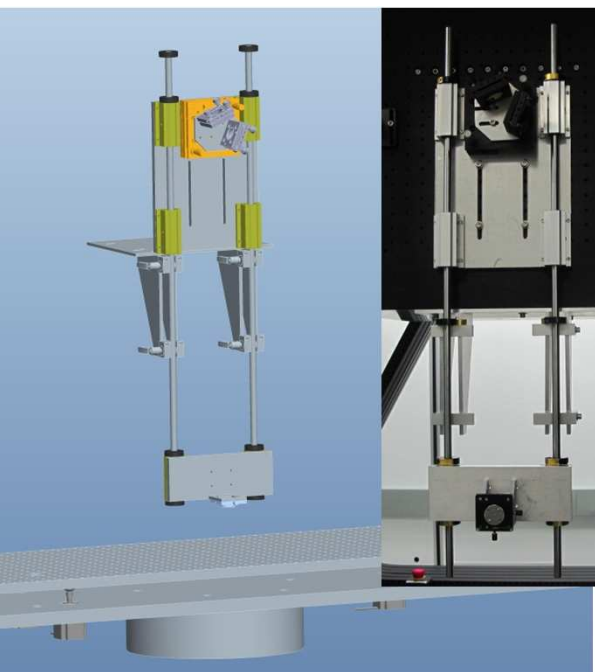
Granite table

Peak-to-Valley <0.05 deg.

camera measurement (by Jeff Collins)



Preliminary tests performed using an AC and a mirror pentaprism (NOM concept)



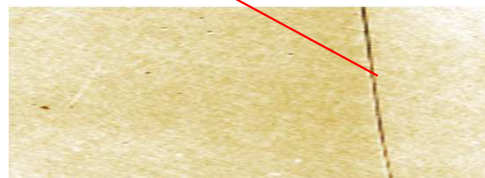
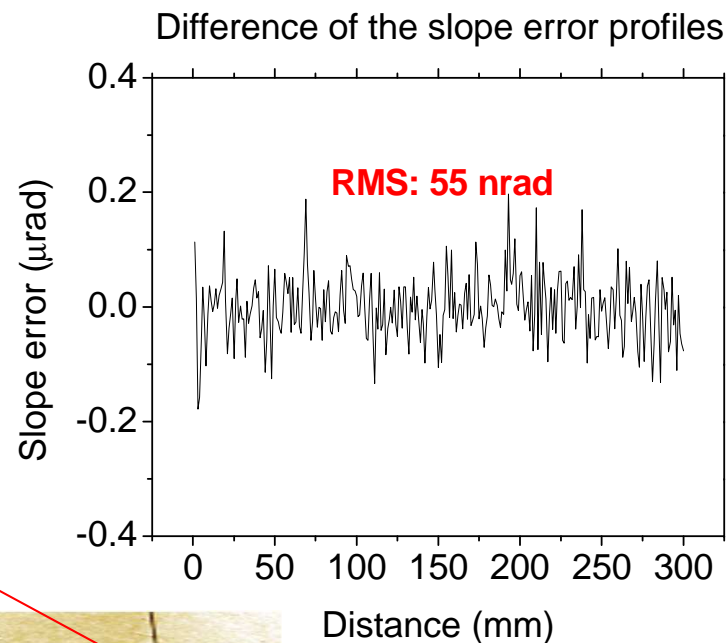
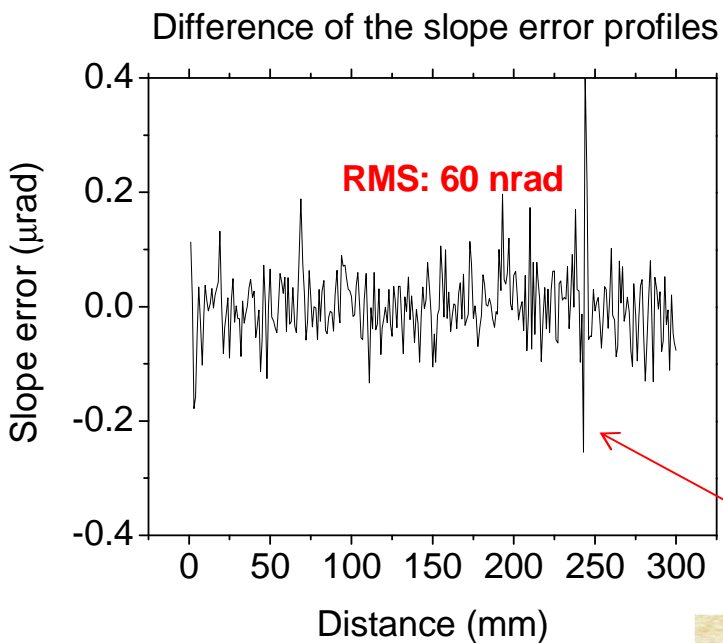
January 2012: first measurements carried out using 350 mm Si mirror (see talk by Jun
on Friday)

May 2012: Characterization of the gantry system (carried out in collaboration with ALS)
ewert, H. Lammert, T. Zeschke, Modern Developments in X-ray and Neutron Optics,
ger 2008

Repeatability measurements on 350 mm flat Si mirror

Large spike due to defect in the mirror,
possibly for positioning error

More representative with the large spike
filtered ...





Issues to be addressed and Future Work

Improve long term temperature stability

Improve the data acquisition

Develop the data analysis software

Complete the comprehensive characterization tests initiated in May 2012 in collaboration with ALS

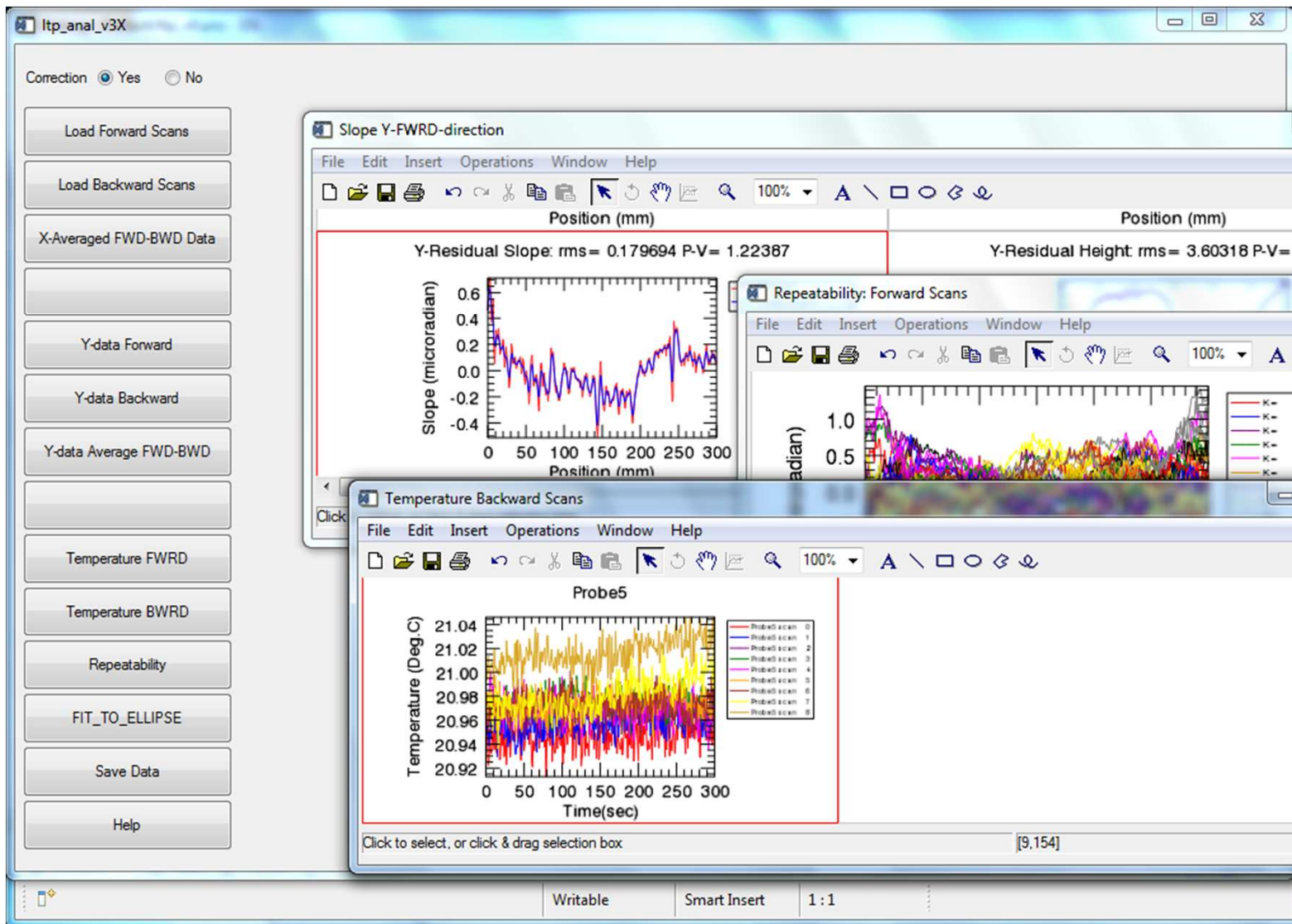
Develop and integrate new slope sensors

Develop standard calibration tools and methods

A new series of worldwide Round robin measurements may be helpful

Suggestion for further improvement are welcome!

Analysis Software





Summary

We developed a high-performance metrology gantry system with the goal to develop a new generation of optical slope measuring system (OSMS)

The system is designed to :

- be modular, with multi-functional translation/scanning capability
- accommodate multiple sensors to cover a wide range of measurement needs in 1-D and 2-D.
- achieve absolute accuracy <50 nrad

The first gantry system was built by ALIO Industries (USA) for APS and commissioned January 2012

Preliminary rounds of tests achieved satisfactory results:

- <70 nrad repeatability was obtained using the NOM configuration, thus meeting the APS goal for Phase-I of the development

Future work (Phase-II): Achieve <50 nrad absolute accuracy. This requires:

- Improving the temperature stability and data acquisition software
- Developing and implementing: 1) advanced sensors, 2) advanced calibration tools and methods, and 3) data analysis and processing software

These enhancements and others will contribute to the development of the next system to be acquired by ALS



Acknowledgements

Wulf Geckler and Michael Shultz (PTB) : autocollimator calibration & useful interaction

John Alcock (Diamond Light Source), Amparo Vivo (ESRF) and Haruhiko Ohashi (Spring-8) for useful interaction

Wolfgang Bender and Curt Preissner (APS): Mechanical engineering

John Collins (APS): Temperature survey

John Sidarous, Andy Stevens, Marvin Kirshenbaum (APS): Enclosure

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Contract # DE-AC02-06CH11357

Thank you!



Extra Slides